Al-Assisted Autonomous Navigation

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Moral dilemma of autonomous vehicles

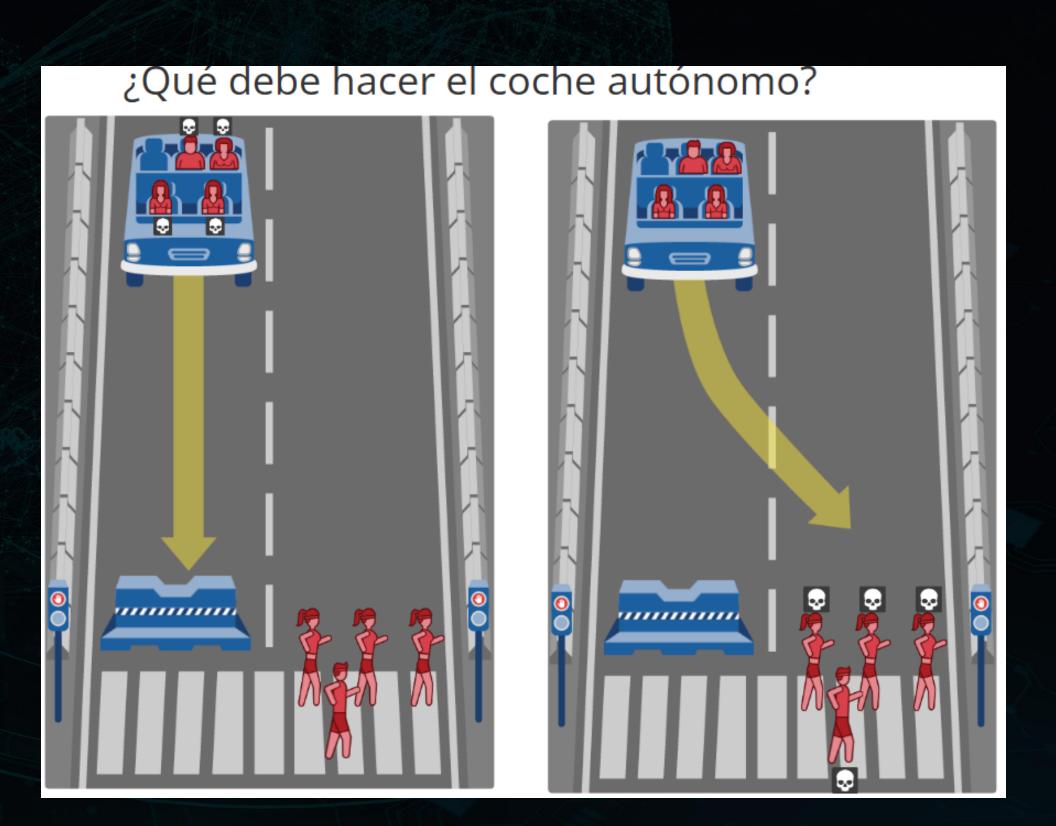




The Moral Machine: An MIT Experiment

https://www.moralmachine.net/hl/es

What solution are self-driving car developers adopting? We'll cover it at the end of the presentation... Don't miss out!







What do we call autonomous navigation?

A device that is capable of moving from one point to another in space, without any human control, and adapting to the dynamic environment that surrounds it.







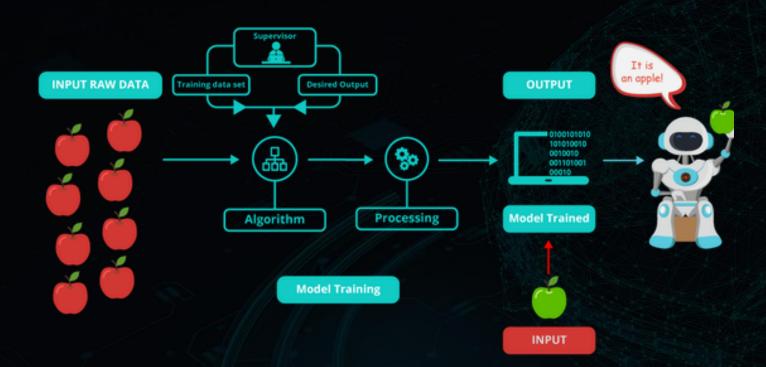
Autonomous navigation issues

- Real-time recognition of the dynamic environment
- Positioning
- Short-term and long-term planning
- In drones and submarines: 3D movement and maintenance in the fluid.



In what aspects does Al play an essential role?

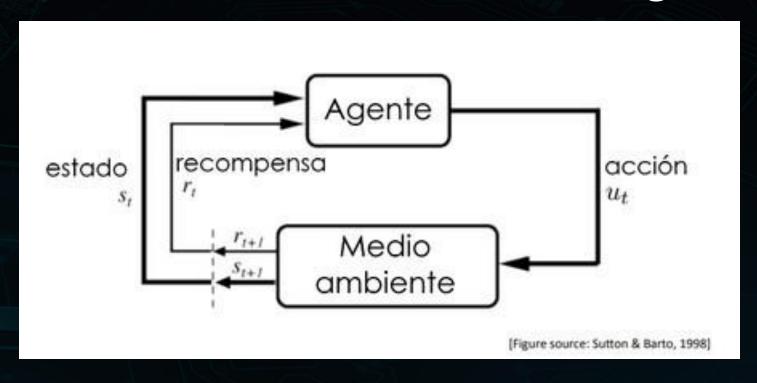




Supervised Learning

A brief review

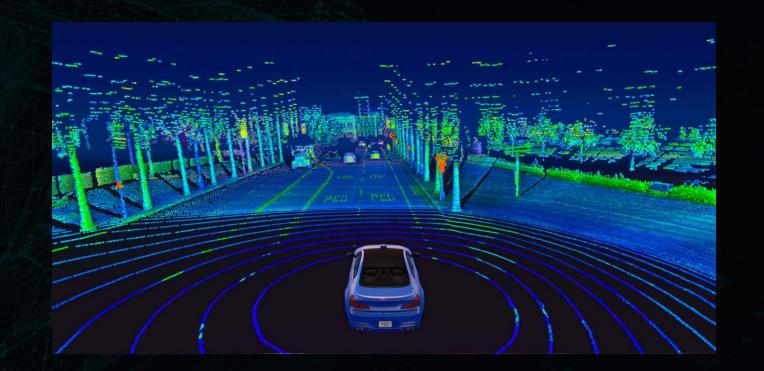
Reinforcement learning





Real-time recognition of the dynamic environment

- Main sensors: lidar and camera
- Global static elements database
- Did any of you participate in the training of an Al for autonomous vehicles?
- Simulators for reinforcement learning
- Relatively tidy environment
- Speed vs precision





Positioning

- Local and global
- Main sensors: gps (global), ultrasonic and lidar (local), environment info
- Using Al for local
- Additional signals in the environment to improve the local position
- Speed vs precision (once again...)





Lidar in soccer



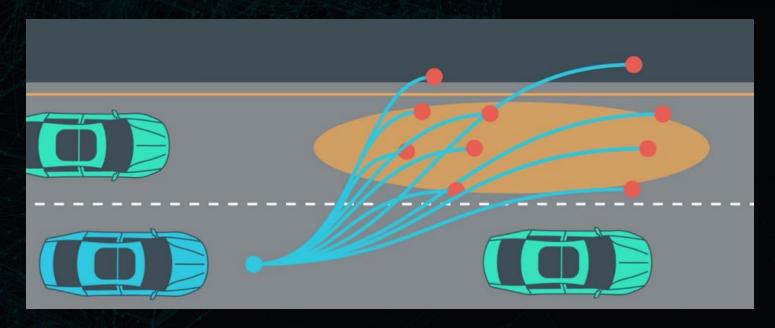
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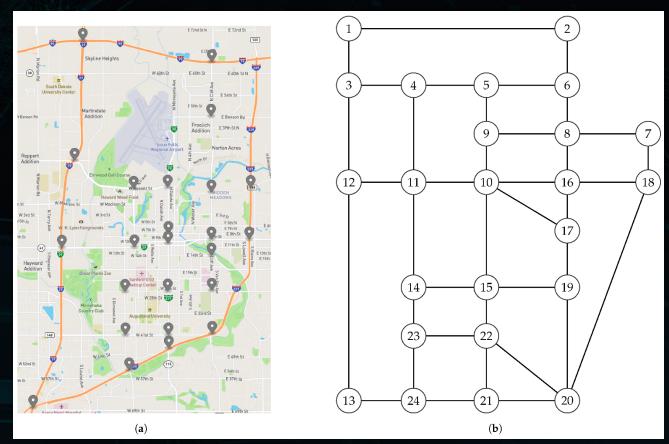
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Short-term and longterm planning

- Main sensors: GPS,
 Environment Info and Global
 Mapping System
- Using Al for local and route optimization
- Path-planning algorithms
 (Traveling salesman problem?)





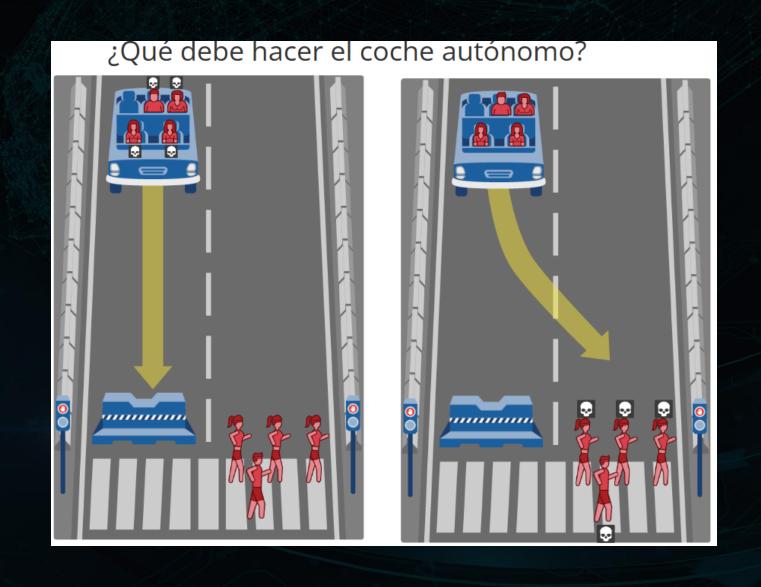




Using Simulators for Reinforcement Learning



Hey, don't forget the solution to the moral problem of self-driving cars!









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